

Investigation into Numerical Models of New High Temperature Superconductors

Chad Sockwell

Florida State University

kcs12j@my.fsu.edu

April 23, 2015

- 1 Superconductivity
- 2 The Ginzburg Landau Model

What is Superconductivity?

- A hallmark property of superconductivity is zero electrical resistance when a metal is supercooled.
- This property persists below a critical temperature T_c .
- This phenomena was first discovered by Onnes in 1911.

$$\rho = \frac{1}{\sigma} = 0 \quad (1)$$

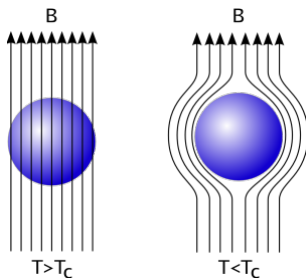
$$\sigma = \frac{1}{\rho} \longrightarrow \infty \quad (2)$$

where ρ is the resistivity and σ is the conductivity.

- What are other properties of superconductors?

The Meissner Effect

- The Meissner Effect occurs when a superconducting material is supercooled in an external magnetic field.
- The field induces super currents on the surface of the material that keep the material from penetrating the sample
- This persists until the field reaches a critical strength H_c
- This is known as the thermodynamic critical field



- Do all superconducting materials react in the same manner?

Type I and Type II superconductors

- Type I superconductors lose all superconducting properties once $\mathbf{H} > \mathbf{H}_c$
- Type II superconductors experience a mixed-state where the sample is penetrated by magnetic flux vortices
- This behavior is exhibited for Type II superconductors beyond a field strength of $\mathbf{H} > \mathbf{H}_{c,1}$
- Once a second critical field strength is reached, $\mathbf{H} > \mathbf{H}_{c,2}$, superconductivity is destroyed
- Thus Type II superconductors have two critical fields and below $\mathbf{H}_{c,1}$ the full Meissner effect is exhibited

Applied Currents

- An current can can be carried very efficiently in a superconductor.
- The superconducting properties are destroyed once the a critical current density \mathbf{J}_c is reached.
- The applied current induces a field, found by $\mathbf{J}_a = \nabla \times \mathbf{H}_a$.
- In Type II superconductors this spatially dependent field produces vortices and move them across the sample.

Applied Currents in Type II Superconductors

- The movement of vortices will eventually create large normal sites and destroy superconductivity.
- The situation is more complicated when an external field \mathbf{H}_e is involved.
- To prevent this, the vortices can be pinned by a pinning force F_p

$$F_p = \mathbf{J}_a \times \mathbf{H}_e \quad (3)$$

- Typically this force is provided by some impurity or imperfection in the material, that give a preferential position for the vortex.

High Temperature Superconductors

- Most materials do not exhibit superconducting properties until they are cooled very close to 0K.
- More recently superconductors with higher critical temperature were discovered
- Once such material is Magnesium Diboride (MgB_2), discovered in 2001, a type II material with $T_c = 39K$
- However this material comes with some odd properties not associated with low temperature superconductors such as anisotropy in the upper critical magnetic field $H_{c,2}$ and an upward curvature in the field as a function of temperature.

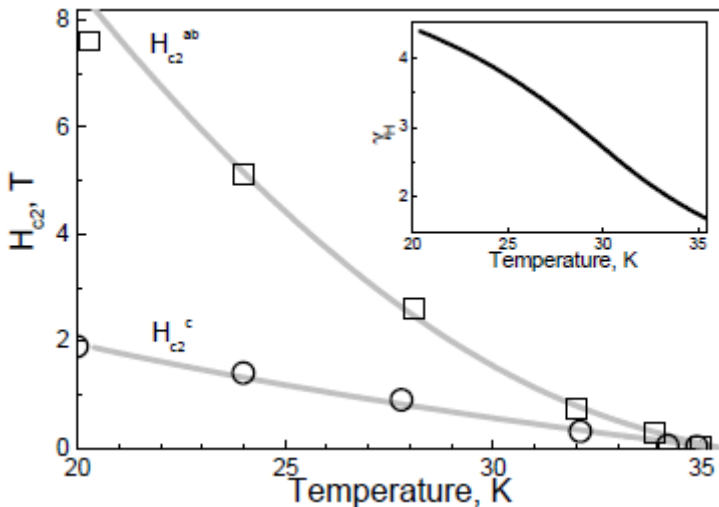


Image from V. H. Dao, M. E. Zhitomirsky: Anisotropy of the upper critical field in MgB₂.

Modeling Vortex Dynamics and Applied current

- Can we model the vortex dynamics in a superconductor with an applied current?
- Can we use the model to make predictions or investigate how to enhance certain properties?

- Ginzburg and Landau derived a free energy functional describing a superconductor in magnetic field (1950)
- Gor'kov proved this to be a limiting case of the microscopic BCS theory in 1959
- In the model, a complex order parameter ψ describes the density of superconducting electrons by $|\psi|^2 = n_s$. ψ and the magnetic vector potential \mathbf{A} are the variables of interest.

The free energy functional

$$G = F_n + \int_{\Omega} \alpha(T)|\psi|^2 + \frac{1}{2}\beta(T)|\psi|^4 + \frac{1}{2m^*} |(-i\hbar\nabla - \frac{e^*}{c}\mathbf{A})\psi|^2 + \frac{|\mathbf{h} - \mathbf{H}_e|^2}{8\pi} d\Omega \quad (4)$$

- $\alpha < 0$ when the sample is in the superconducting state and $\beta > 0$
- F_n is the free energy in the normal state, the α and β terms are the energy from the phase transition
- The next terms is the kinetic energy of the superconducting electrons using the gauge invariant derivate
- The last term is the energy associated from the induced and external magnetic fields, with $\mathbf{h} = \nabla \times \mathbf{A}$

Finding the Minimizers

- Using calculus of variations, the Euler-Lagrange equations of the free energy functional can be found.

$$\lim_{\epsilon \rightarrow 0} \frac{G(\psi + \epsilon \tilde{\psi}) - G(\psi)}{\epsilon} = 0 \quad (5)$$

$$\lim_{\epsilon \rightarrow 0} \frac{G(\mathbf{A} + \epsilon \tilde{\mathbf{A}}) - G(\psi)}{\epsilon} = 0 \quad (6)$$

The Ginzburg Landau Equations

- The Euler-Lagrange equations of the free energy functional are the Ginzburg Landau Equations.
- Let Ω be a square superconducting sample in the x,y plane and let $\partial\Omega$ be its boundary.

$$\alpha(T)\psi + \beta(T)|\psi|^2\psi + \frac{1}{2m^*}(-i\hbar\nabla - \frac{e^*\mathbf{A}}{c})^2\psi = 0, \quad \text{in } \Omega \quad (7)$$

$$\frac{1}{4\pi}\nabla \times (\nabla \times \mathbf{A} - \mathbf{H}) = \frac{-ie^*\hbar}{2m^*}(\psi^*\nabla\psi - \psi\nabla\psi^*) - \frac{e^{2*}}{m^*c}|\psi|^2\mathbf{A} = \mathbf{J}_s, \quad \text{in } \Omega \quad (8)$$

with boundary conditions for an insulating boundary:

$$\begin{aligned} (-i\hbar\nabla - \frac{e^*}{c}\mathbf{A})\psi \cdot \mathbf{n} &= 0, \quad \text{on } \partial\Omega \\ (\nabla \times \mathbf{A} - \mathbf{H}_e) \times \mathbf{n} &= 0, \quad \text{on } \partial\Omega \end{aligned} \quad (9)$$

Normal Metal-Superconducting Boundary Conditions

- For normal metal superconducting interfaces, some of the superconducting electrons leak into the normal metal, through the Josephson effect.
- This effect can be captured by including the following term in the free energy functional

$$\int_{\partial\Omega} \zeta |\psi|^2 \quad (10)$$

- This generates the S-N boundary condition

$$\left(-i\hbar\nabla - \frac{e^*}{c}\mathbf{A}\right)\psi \cdot \mathbf{n} = i\hbar\zeta\psi \quad \text{on } \partial\Omega \quad (11)$$

- To include the time dependence in the Ginzburg Landau equations, lets rearrange the free energy as,

$$G = F_s + \int_{\Omega} \frac{|\mathbf{h} - \mathbf{H}_e|^2}{8\pi} d\Omega \quad (12)$$

- The variation in the free energy with respect can be set equal to a small disturbance in the equilibrium of the sample. The inclusion of Φ , the electrical potential, is to ensure the gauge invariance.

$$\Gamma\left(\frac{\partial\psi}{\partial t} + \frac{ie^*}{\hbar}\Phi\psi\right) = -\frac{\delta G}{\delta\psi^*} \quad (13)$$

Time dependence (Continued)

- To include the time dependence in vector potential equation, let J_n and J_s be the normal current and super current densities respectively,

$$\begin{aligned}\mathbf{J}_n &= \sigma_n \mathbf{E} = -\sigma_n \left(\frac{1}{c} \frac{\partial \mathbf{A}}{\partial t} + \nabla \Phi \right) \\ \mathbf{J}_s &= -c \frac{\partial F_s}{\partial \mathbf{A}} = -\left(\frac{ie^* \hbar}{2m^*} (\psi^* \nabla \psi - \psi \nabla \psi^*) + \frac{e^{*2}}{m^* c} |\psi|^2 \mathbf{A} \right)\end{aligned}\tag{14}$$

- The total current in the superconducting sample is,

$$\mathbf{J} = \mathbf{J}_n + \mathbf{J}_s = \sigma_n \left(-\frac{1}{c} \frac{\partial \mathbf{A}}{\partial t} - \nabla \phi \right) - c \frac{\partial F_s}{\partial \mathbf{A}}\tag{15}$$

Temperature Dependence

- Using the BCS theory, the Temperature dependence can be separated from the material dependent constants $\alpha(T)$ and $\beta(T)$ when $T \approx T_c$

$$\begin{aligned}\alpha(T) &\approx -\alpha(0)\left(1 - \frac{T}{T_c}\right) = \alpha\left(1 - \frac{T}{T_c}\right) \\ \beta(T) &\approx \frac{7\zeta(3)\nu(0)}{8\pi^2 T_c^2} = \beta\end{aligned}\tag{16}$$

- What is $T \approx T_c$?

The Time Dependent Ginzburg Landau Equations

- Combing the time and temperature dependencies

$$\Gamma\left(\frac{\partial\psi}{\partial t} + \frac{ie}{\hbar}\Phi\psi\right) + \alpha\left(1 - \frac{T}{T_c}\right)\psi + \beta|\psi|^2\psi + \frac{1}{2m^*}\left(-i\hbar\nabla - \frac{e^*\mathbf{A}}{c}\right)^2\psi = 0, \text{ in } \Omega \quad (17)$$

$$\begin{aligned} & \frac{1}{4\pi}\nabla \times (\nabla \times \mathbf{A} - \mathbf{H}) = \\ \sigma_n\left(-\frac{1}{c}\frac{\partial A}{\partial t} - \nabla\Phi\right) + \frac{-ie^*\hbar}{2m^*}(\psi^*\nabla\psi - \psi\nabla\psi^*) - \frac{e^{*2}}{m^*c}|\psi|^2\mathbf{A}, \text{ in } \Omega \end{aligned} \quad (18)$$

with initial and boundary conditions:

$$\begin{aligned} (-i\hbar\nabla - \frac{e_s}{c}\mathbf{A})\psi \cdot \mathbf{n} &= 0, \text{ on } \partial\Omega \text{ and } \forall t \\ (\nabla \times \mathbf{A} - H_e) \times \mathbf{n} &= 0, \text{ on } \partial\Omega \text{ and } \forall t \\ \psi(x, 0) &= \psi_0(x), \text{ on } \Omega \\ \mathbf{A}(x, 0) &= \mathbf{A}_0(x), \text{ on } \Omega \end{aligned} \quad (19)$$

The Time Dependent Ginzburg Landau Equations(continued)

- The TDGL equations can be used to model vortex dynamics.
- First we must discuss important parameters and gauge the system.
- The penetration depth λ is material specific and is shown in the Meissner effect.

$$\Delta \mathbf{H} = \frac{1}{\lambda^2} \mathbf{H} \quad (20)$$

- The coherence length ξ is the characteristic length of change of ψ
- The Ginzburg Landau parameter is the ratio $\kappa = \frac{\lambda}{\xi}$

$$\lambda(T) = \sqrt{-\frac{m^* \beta c^2}{4\pi \alpha(T) e^{2*}}} \quad \xi(T) = \sqrt{-\frac{\hbar^2}{2m^* \alpha(T)}} \quad (21)$$

Some Important Parameters

- $\kappa < \frac{1}{\sqrt{2}}$ for Type I and $\kappa > \frac{1}{\sqrt{2}}$ for Type II
- The value of ψ deep inside a superconducting sample is known as the solution in the bulk, ψ_∞ , found by solving,

$$\alpha(T)\psi + \frac{1}{2}\beta(T)|\psi|^2\psi = 0 \quad (22)$$

$$\psi_\infty = \sqrt{\frac{-\alpha}{\beta}} \quad (23)$$

- The thermodynamic critical can defined in terms of free energy densities.

$$f_s - f_n = \frac{-H_c^2}{8\pi} = \frac{-\alpha^2}{\beta} \quad (24)$$

Gauging the system

- Since we have three variable ψ, \mathbf{A}, Φ , and two equations, the system needs to be closed
- This can be done by using the zero potential gauge

$$\frac{\partial \chi}{\partial t} = \Phi = 0 \quad (25)$$

- with initial conditions (at $t = 0$),

$$\begin{aligned} \Delta \chi &= -\nabla \cdot \mathbf{A} \text{ on } \Omega \\ \nabla \chi \cdot \mathbf{n} &= -\mathbf{A} \cdot \mathbf{n} \text{ on } \partial \Omega \end{aligned} \quad (26)$$

Non-Dimensionalization

- To introduce the characteristic length λ , and ξ , as well as rescale the system the TDGL equations are non-dimensionalized.
- Using the following non dimensionalized variables (with bars)

$$\begin{aligned}x &= x_0 \bar{x}, & t &= \bar{t} \frac{(-\alpha)}{\Gamma \hbar} \\ H_c &= \sqrt{\frac{8\pi\alpha^2}{\beta}}, & \mathbf{A} &= H_c x_0 \bar{\mathbf{A}} \\ \mathbf{H} &= \sqrt{2} H_c \bar{\mathbf{H}} & \psi &= \sqrt{\frac{-\alpha}{\beta}} \bar{\psi} \\ \lambda &= \sqrt{-\frac{c^2 m^* \beta}{4\pi e^{*2} \alpha}}, & \xi &= \sqrt{-\frac{\hbar^2}{2m^* \alpha}} \\ \sigma_n &= \frac{\Gamma c^2}{2\pi \hbar} \bar{\sigma}, & \Phi &= \frac{-\alpha}{\Gamma} \bar{\Phi}\end{aligned} \tag{27}$$

- The non-dimensionalized TDGL equations in the zero potential gauge equations are suitable for numerical calculations

$$\left(\frac{\partial\psi}{\partial t}\right) + (|\psi|^2 - (1 - \frac{T}{T_c})\psi + (-i\frac{\xi}{x_0}\nabla - \frac{x_0}{\lambda}\mathbf{A})^2\psi = 0 \quad (28)$$

$$\sigma\left(\frac{1}{\lambda^2}\frac{\partial\mathbf{A}}{\partial t}\right) + \nabla \times \nabla \times \mathbf{A} + \frac{i}{2\kappa}(\psi\nabla\psi^* - \psi^*\nabla\psi) + \frac{1}{\lambda^2}|\psi|^2\mathbf{A} = \nabla \times \mathbf{H}_e \quad (29)$$

$$\begin{aligned} \nabla\psi \cdot \mathbf{n} &= 0, \text{ on } \partial\Omega \text{ and } \forall t \\ (\nabla \times \mathbf{A} - H_e) \times \mathbf{n} &= 0, \text{ on } \partial\Omega \text{ and } \forall t \\ \mathbf{A} \cdot \mathbf{n} &= 0, \text{ on } \partial\Omega \text{ and } \forall t \\ \nabla \cdot \mathbf{A}(\mathbf{x}, 0) &= 0 \quad \Omega \\ \psi(\mathbf{x}, 0) &= \psi_0(\mathbf{x}), \Omega \\ \mathbf{A}(\mathbf{x}, 0) &= \mathbf{A}_0(\mathbf{x}), \Omega \end{aligned} \quad (30)$$

Finite Element Method

- The finite element method is used to approximate solutions of partial differential equations such as the TDGL equations
- The partial differential equations must be put in the weak form.
- This is done by multiplying by a test function from a vector space V and integrating by parts over the spatial domain.
- Boundary conditions on the solution are enforced on the test space V , while the ones on the derivative are naturally included.
- Then the problem is stated as find a solution in the space V that solve the weak form all test functions in the space V

Finite Element Method (Continued)

- The method is implemented numerically by discretizing the domain Ω in to element.
- The vector space V is also discretized into basis functions defined in a piecewise manner on the elements.
- A system of equations is formed and solved to give a continuous solution over the domain.
- The detail of the specific finite element implementation can be seen in the thesis

- The finite element codes were written and verified for problems with exact solutions
- This was extended to multi-variable, non-linear, and time dependent problems to prepare for the TDGL.

- The backward Euler method (first order convergence) was used to approximate the time derivative

$$\left. \frac{\partial \psi}{\partial t} \right|_{t=t_n} \approx \frac{\psi(t_n) - \psi(t_{n-1})}{\Delta t} \quad (31)$$

- The forward Euler method is not used because it offer no advantage. Higher order implicit methods will give greater accuracy but come at a cost.

The Weak Form

- The weak problem is stated as seek a solution $\psi \in V$ and $\mathbf{A} \in \mathbf{Z}$ and test against all $\tilde{\psi} \in V$ and $\tilde{\mathbf{A}} \in \tilde{\mathbf{Z}}$ in Ω

$$\left(\frac{\partial \psi}{\partial t}, \tilde{\psi}\right) + ([|\psi|^2 - \tau)\psi], \tilde{\psi}) + \left(-i \frac{\xi}{x_0} \nabla \psi - \frac{x_0}{\lambda} \mathbf{A} \psi, -i \frac{\xi}{x_0} \nabla \tilde{\psi} - \frac{x_0}{\lambda} \mathbf{A} \tilde{\psi}\right) = 0 \quad (32)$$

$$\begin{aligned} & \sigma \left(\frac{1}{\lambda^2} \frac{\partial \mathbf{A}}{\partial t}, \tilde{\mathbf{A}} \right) + (\nabla \times \mathbf{A}, \nabla \times \tilde{\mathbf{A}}) + \epsilon (\nabla \cdot \mathbf{A}, \nabla \cdot \tilde{\mathbf{A}}) \\ & + \left(\frac{i}{2\kappa} [\psi \nabla \psi^* - \psi^* \nabla \psi], \tilde{\mathbf{A}} \right) + \left(\frac{1}{\lambda^2} |\psi|^2 \mathbf{A}, \tilde{\mathbf{A}} \right) = (\mathbf{H}_e, \nabla \times \tilde{\mathbf{A}}) \quad (33) \\ & \tau = \left(1 - \frac{T}{T_c}\right) \end{aligned}$$

- with initial conditions

$$\begin{aligned} \nabla \cdot \mathbf{A}(\mathbf{x}, 0) &= 0 \quad \Omega \\ \psi(\mathbf{x}, 0) &= \psi_0(\mathbf{x}), \Omega \\ \mathbf{A}(\mathbf{x}, 0) &= \mathbf{A}_0(\mathbf{x}), \Omega \end{aligned} \quad (34)$$

Weak Form (continued)

- The inner product (\cdot, \cdot) is defined as,

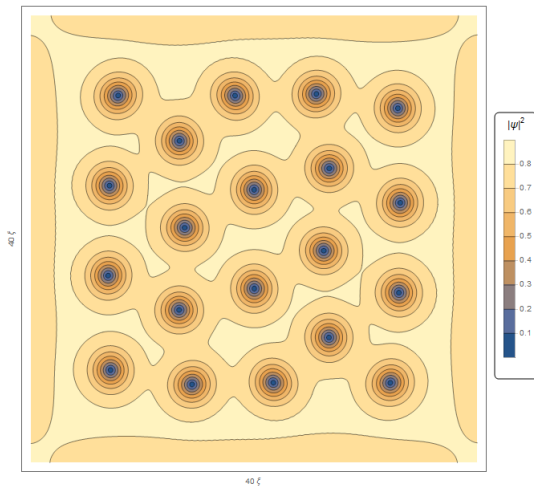
$$(f, g) = \int_{\Omega} f^* \cdot g \, d\Omega \quad (35)$$

- The penalty term, $\epsilon(\nabla \cdot \mathbf{A}, \nabla \cdot \tilde{\mathbf{A}})$ is used to help convergence and is proved to give the correct steady state by Du.

An FEM approximation

- Using FEM we can approximate the solutions of the TDGL equations and show evolution of vortex dynamics as well as the steady state.
- Consider a Type II superconductor with the following parameters
- In Figure 3.1 is an example of the order parameter ψ for $\lambda = 60nm$, $\xi = 5nm$, $(1 - \frac{T}{T_c}) = 0.7$, $\frac{T}{T_c} = 0.3$, $\mathbf{H}_e = 1.5 = 1.5\sqrt{2}\mathbf{H}_c$. Ω is $20nm \times 20nm$.

Steady State Order Parameter Plot and Movie



Anisotropy

- Some superconductors such as MgB_2 have anisotropic effects, such as the anisotropy in $\mathbf{H}_{c,2}$
- The directional dependent effects can be captured using the effective mass GL model.
- In this model the effective mass m^* is replaced by an anisotropic mass tensor.

$$\mathbf{M} = \begin{pmatrix} m_x & 0 \\ 0 & m_y \end{pmatrix} \quad (36)$$

- This gives a characteristic length in each direction ξ_x, λ_x, ξ_y and λ_y

$$\gamma = \frac{m_x}{m_y} = \left(\frac{\lambda_x}{\lambda_y}\right)^2 = \left(\frac{\xi_y}{\xi_x}\right)^2 = \frac{\mathbf{H}_c}{\mathbf{H}_{a,b}} \quad (37)$$

The Effective Mass Model

$$\left(\frac{\partial \psi}{\partial t}\right) + (|\psi|^2 - \tau)\psi + \left(-i\frac{\xi_x}{x_0}\frac{\partial}{\partial x} - \frac{x_0}{\lambda_x}\mathbf{A}_x\right)^2\psi + \gamma\left(-i\frac{\xi_x}{x_0}\frac{\partial}{\partial y} - \frac{x_0}{\lambda_x}\mathbf{A}_y\right)^2\psi = 0 \quad (38)$$

$$\sigma\left(\frac{1}{\lambda_x^2}\frac{\partial \mathbf{A}}{\partial t}\right) + \nabla \times \nabla \times \mathbf{A} + \left\{\frac{i}{2\kappa}\left(\psi\frac{\partial}{\partial x}\psi^* - \psi^*\frac{\partial}{\partial x}\psi\right) + \frac{x_0^2}{\lambda_x^2}|\psi|^2\mathbf{A}_x\right\} + \gamma\left\{\frac{i}{2\kappa}\left(\psi\frac{\partial}{\partial y}\psi^* - \psi^*\frac{\partial}{\partial y}\psi\right) + \frac{x_0^2}{\lambda_x^2}|\psi|^2\mathbf{A}_y\right\} = \nabla \times \mathbf{H}_e \quad (39)$$

$$\nabla \psi \cdot \mathbf{n} = 0, \text{ on } \partial\Omega \text{ and } \forall t$$

$$(\nabla \times \mathbf{A} - H_e) \times \mathbf{n} = 0, \text{ on } \partial\Omega \text{ and } \forall t$$

$$\mathbf{A} \cdot \mathbf{n} = 0, \text{ on } \partial\Omega \text{ and } \forall t$$

$$\nabla \cdot \mathbf{A}(\mathbf{x}, 0) = 0 \quad \Omega$$

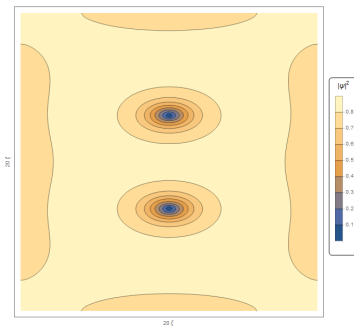
$$\psi(x, 0) = \psi_0(x), \Omega$$

$$\mathbf{A}(x, 0) = \mathbf{A}_0(x), \Omega$$

(40)

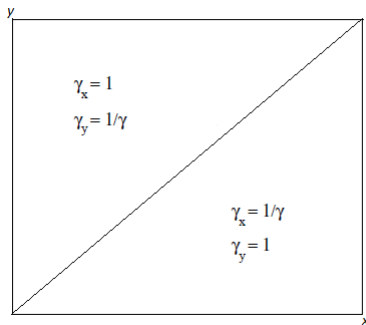
The Effective Mass Model (continued)

- The effects are most pronounced in the vortices, contracting by $\frac{l_x}{l_y} = \sqrt{\frac{m_x}{m_y}}$
- Consider a Type II superconductor on a $10nm \times 10nm$. The parameters are $\lambda = 60nm$, $\xi = 5nm$, $(1 - \frac{T}{T_c}) = 0.7$, $\frac{T}{T_c} = 0.3$, $\mathbf{H}_e = 1.5 = 1.5\sqrt{2}\mathbf{H}_c$, $\gamma = \frac{1}{4}$.



Grain boundaries

- Some anisotropic materials have domain walls where the crystal structure is reoriented
- These are known as grain boundaries, and the anisotropy is changed as the boundary is crossed
- This can be captured by using two functions $\gamma_x(x, y)$ and $\gamma_y(x, y)$, where the anisotropy is flipped across the boundary



The Two Band Model

- Multi-band superconductivity was used to describe the upward curvature of $\mathbf{H}_{c,2}$ by Dao, Zhitomirsky and others
- The Two band model uses a second order parameter ψ_2 to represent the second band.
- The bands are coupled through Josephson effect like terms (η), inter-gradient coupling (η_1), and through the magnetic vector potential equation.
- The bands have different characteristics and critical temperatures $T_{c,1}$ and $T_{c,2}$, both below the materials critical temperature T_c .
- The coupling between the bands gives superconducting effects above both bands critical temperatures.

$$\begin{aligned} & \left(\frac{\partial \psi_1}{\partial t} + i\Phi\psi_1 \right) + (|\psi_1|^2 - \tau_1)\psi_1 + \left(-i\frac{\xi_1}{x_0}\nabla - \frac{x_o}{\lambda_1}\mathbf{A} \right)^2 \psi_1 \\ & + \eta\psi_2 + \eta_1 \frac{\xi_1}{\nu\xi_2} \left(-i\frac{\xi_2}{x_0}\nabla - \nu\frac{x_o}{\lambda_2}\mathbf{A} \right)^2 \psi_2 = 0 \end{aligned}$$

$$\begin{aligned} & \Gamma \left(\frac{\partial \psi_2}{\partial t} + i\Phi\psi_2 \right) + (|\psi_2|^2 - \tau_2)\psi_2 + \left(-i\frac{\xi_1}{x_0}\nabla - \nu\frac{x_o}{\lambda_1}\mathbf{A} \right)^2 \psi_2 \\ & + \eta\psi_1 + \eta_1 \nu \frac{\xi_2}{\xi_1} \left(-i\frac{\xi_1}{x_0}\nabla - \frac{x_o}{\lambda_1}\mathbf{A} \right)^2 \psi_1 = 0 \end{aligned} \tag{41}$$

$$\nu = \left(\frac{\lambda_2 \xi_1}{\lambda_1 \xi_2} \right)$$

$$\begin{aligned}
 \nabla \times (\nabla \times \mathbf{A} - \mathbf{H}) &= \sigma \left(-\frac{x_0^2}{\lambda_1^2} \frac{\partial A}{\partial t} - \frac{1}{\kappa_1} \nabla \Phi \right) + i \frac{1}{2\kappa_1} (\psi_1 \nabla \psi_1^* - \psi_1^* \nabla \psi_1) \\
 &\quad - \frac{x_0^2}{\lambda_1} |\psi_1|^2 \mathbf{A} + i \frac{1}{2\kappa_2 \nu} (\psi_2 \nabla \psi_2^* - \psi_2^* \nabla \psi_2) - \frac{x_0^2}{\lambda_2} |\psi_2|^2 \mathbf{A} \\
 &\quad + i \eta_1 \frac{\xi_1}{2\lambda_2} (\psi_2 \nabla \psi_1^* - \psi_2^* \nabla \psi_1 + \psi_1 \nabla \psi_2^* - \psi_1^* \nabla \psi_2) \\
 &\quad - \eta_1 \frac{x_0^2}{\lambda_1 \lambda_2} \mathbf{A} (\psi_1 \psi_2^* + \psi_2 \psi_1^*)
 \end{aligned} \tag{42}$$

and non-dimensionalized boundary and initial conditions,

$$\left((-i \frac{\xi_1}{x_0} \nabla - \frac{x_o}{\lambda_1} \mathbf{A}) \psi_1 + \eta_1 \frac{1}{\nu} \left(-i \frac{\xi_1}{x_0} \nabla - \nu \frac{x_o}{\lambda_1} \mathbf{A} \right) \psi_2 \right) \cdot \mathbf{n} = i \zeta_1 \frac{\xi_1}{x_0} \psi_1 \quad \text{on } \partial\Omega \times ($$

$$\left((-i \frac{\xi_1}{x_0} \nabla - \nu \frac{x_o}{\lambda_1} \mathbf{A}) \psi_2 + \eta_1 \nu \left(-i \frac{\xi_1}{x_0} \nabla - \frac{x_o}{\lambda_1} \mathbf{A} \right) \psi_1 \right) \cdot \mathbf{n} = i \zeta_2 \frac{\xi_2}{x_0} \psi_2 \quad \text{on } \partial\Omega \times ($$

$$(\nabla \times \mathbf{A}) \times \mathbf{n} = \mathbf{H}_e \times \mathbf{n} \quad \text{on } \partial\Omega \times (0, t')$$

$$\psi_1(x, y, 0) = \psi_{1,0}(x, y) \quad \text{on } \Omega$$

$$\psi_2(x, y, 0) = \psi_{2,0}(x, y) \quad \text{on } \Omega$$

$$\mathbf{A}(x, y, 0) = A_0(x, y) \quad \text{on } \Omega$$

(43)

ND TB-TDGL (Continued)

The non-dimensionalizations are

$$\begin{aligned}x &= x_0 \bar{x}, & t &= \bar{t} \frac{(-\alpha)}{\Gamma_1 \hbar} \\ H_c &= \sqrt{\frac{8\pi\alpha_1^2}{\beta_1}}, & \mathbf{A} &= H_c x_0 \bar{\mathbf{A}} \\ \Phi &= \frac{\hbar(-\alpha_1)}{2\Gamma_1 e^*} \bar{\Phi}, & \Gamma &= \frac{\Gamma_1(-\alpha_1)}{\Gamma_2(-\alpha_2)} \\ \kappa_i &= \sqrt{\frac{c^2 m_i^* \beta_i}{2\pi e^{*2} \hbar^2}} & \nu &= \frac{\lambda_2 \xi_2}{\lambda_1 \xi_1} = \sqrt{\frac{\alpha_1^2 \beta_2}{\alpha_2^2 \beta_1}} \\ \eta &= \eta_1 \sqrt{\frac{\beta_1 \alpha_2}{\beta_2 \alpha_1}} \frac{1}{\alpha_1} & \eta_1 &= \epsilon_1 2 \sqrt{m_1^* m_2^*} \\ \sigma &= \frac{\sigma_n m_1^* \beta_1}{\Gamma_1 e^{*2}}\end{aligned} \tag{44}$$

- The TB-TDGL can be put in the current gauge to include an applied current in the sample

$$\mathbf{J}_a = -\frac{\sigma}{\kappa_1} \nabla \Phi \leftrightarrow \Phi_a = -\frac{\kappa_1}{\sigma} J_a y \quad (45)$$

$$\mathbf{J}_a = \nabla \times \mathbf{H}_{app} \leftrightarrow \mathbf{H}_{app} = -J_a \left(x - \frac{x_0}{2}\right) \hat{z} \quad (46)$$

- Assuming the applied current is in the y direction and the S-N interface is used
- The first relation is used in the ψ equations, and the second is used in the \mathbf{A} equation.

Modeling Magnesium Diboride

- MgB_2 is a layered, two-band, type II material, with $T_c = 39$ and containing a strong anisotropy in its upper critical field
- Superconducting bands are the anisotropic σ band and the isotropic π band
- It also possesses clean grain boundaries where the anisotropy is changed but does not impede applied current
- This allows for the practical use of MgB_2 for carrying current.
- Using our previous model we can make a model to capture all these properties.

Table 4.1

$\xi_{\sigma}(0) = 13nm$	$\lambda_{\sigma}(0) = 47.81nm$	$\kappa_{\sigma} = 3.68$
$\xi_{\pi}(0) = 51nm$	$\lambda_{\pi}(0) = 33.6nm$	$\kappa_{\pi} = 0.66$
$T_c = 39K$	$T_{c,\sigma} = 35.6K$	$T_{c,\pi} = 11.8K$
$\gamma_{\sigma} = 4.55$	$\gamma_{\pi} = 1$	$T = 31K$

Table : These are the parameters for a clean sample MgB_2 .

The Anisotropic 2B-TDGL w/ Applied Current and a Grain Boundary (Weak Form)

$$\int_{\Omega} \frac{\partial \psi_1}{\partial t} \tilde{\psi} - i \frac{\kappa_1}{\sigma} J_a y \sin(\omega t) \psi_1 \tilde{\psi} + (|\psi_1|^2 - \tau_1) \psi_1 \tilde{\psi} + \mathbf{D}_1 \psi_1 \cdot \boldsymbol{\gamma} \cdot \mathbf{D}_1 \tilde{\psi}_1 + \eta \psi_2 \tilde{\psi} + \eta_1 \frac{\xi_1}{\nu \xi_2} \mathbf{D}_2 \psi_2 \cdot \boldsymbol{\gamma} \cdot \mathbf{D}_2 \tilde{\psi} d\Omega = - \int_{\partial\Omega} \zeta_1 \frac{\xi_1^2}{x_0} \psi_1 \tilde{\psi} dS \quad (47)$$

$$\int_{\Omega} \Gamma \frac{\partial \psi_2}{\partial t} \tilde{\psi} - i \frac{\kappa_1}{\sigma} J_a y \sin(\omega t) \psi_1 \tilde{\psi}_2 + (|\psi_2|^2 - \tau_2) \psi_2 \tilde{\psi} + \mathbf{D}_2 \psi_2 \cdot \mathbf{D}_2 \tilde{\psi} + \eta \psi_1 \tilde{\psi} + \eta_1 \frac{\xi_2}{\xi_1} \mathbf{D}_1 \psi_1 \cdot \boldsymbol{\gamma} \cdot \mathbf{D}_1 \tilde{\psi} d\Omega = - \int_{\partial\Omega} \zeta_2 \frac{\xi_2^2}{x_0} \psi_2 \tilde{\psi} dS \quad (48)$$

$$\boldsymbol{\gamma} = \begin{pmatrix} \frac{1}{\gamma_x(x,y)} & 0 \\ 0 & \frac{1}{\gamma_y(x,y)} \end{pmatrix} \quad \mathbf{D}_1 = \left(-i \frac{\xi_1}{x_0} \nabla - \frac{x_0}{\lambda_1} \mathbf{A}\right), \quad \mathbf{D}_2 = \left(-i \frac{\xi_2}{x_0} \nabla - \nu \frac{x_0}{\lambda_2} \mathbf{A}\right)$$

$$\begin{aligned}
& \int_{\Omega} \sigma \frac{x_0^2}{\lambda_1^2} \frac{\partial \mathbf{A}}{\partial t} \tilde{\mathbf{A}} + \epsilon (\nabla \cdot \mathbf{A}) \cdot (\nabla \cdot \tilde{\mathbf{A}}) + (\nabla \times \mathbf{A}) \cdot (\nabla \times \tilde{\mathbf{A}}) + \\
& \quad \mathcal{R} \left\{ i \frac{1}{\kappa_1} (\boldsymbol{\gamma} \cdot \nabla \psi_1) \cdot \psi_1 \cdot \tilde{\mathbf{A}} \right\} + \frac{x_0^2}{\lambda_1^2} |\psi_1|^2 \boldsymbol{\gamma} \cdot \mathbf{A} \cdot \tilde{\mathbf{A}} \\
& \quad + \mathcal{R} \left\{ i \frac{1}{\nu \kappa_1} (\nabla \psi_2) \cdot \psi_2 \tilde{\mathbf{A}} \right\} + \frac{x_0^2}{\lambda_2^2} |\psi_2|^2 \mathbf{A} \cdot \tilde{\mathbf{A}} \\
& + \eta_1 \boldsymbol{\gamma} \cdot \left(\mathcal{R} \left\{ i \frac{\xi_1}{\lambda_2} (\cdot \nabla \psi_1) \cdot \psi_2 \tilde{\mathbf{A}} \right\} + \mathcal{R} \left\{ i \frac{\xi_1}{\lambda_2} (\cdot \nabla \psi_2) \cdot \psi_1 \tilde{\mathbf{A}} \right\} \right) \\
& \quad + \eta_1 \frac{x_0}{\lambda_1 \lambda_2} \boldsymbol{\gamma} \cdot \{ (\psi_1 \psi_2^* + \psi_2 \psi_1^*) \mathbf{A} \cdot \tilde{\mathbf{A}} \} d\Omega \\
& = \int_{\Omega} (\mathbf{H}_e - J_a \sin(\omega t) (x - \frac{x_0}{2} \hat{z})) \cdot (\nabla \times \tilde{\mathbf{A}}) d\Omega
\end{aligned} \tag{49}$$

Investigating the effect of η on the critical temperature

- We can use this model for numerical studies to investigate the effect of the order parameter
- The non dimensionlized values can used and the results can tell experimentalist how to tune dimensionalized parameters
- Effects seen in the study may lead to improvement in the material if possible
- We also verify things that are know experimentally

Critical Current Vs Applied field for MgB_2 at various T

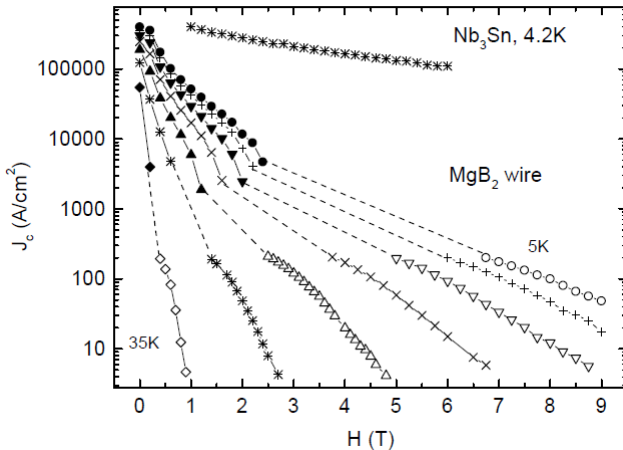


Image from An Overview of the Basic Physical Properties of MgB_2 P.C. Canfield, S.L. Budko, D.K. Finnemore

Numerical studies

- For example 1 $J_a = 20$ to see if this value exceed the critical current. The sample contains a grain boundary across the diagonal ($x = y$ line) where the anisotropy flips from the y direction to the x directions. Here $\eta = 0.8$ (strong coupling), $\mathbf{H}_e = 1.6$ (moderate), $\zeta_{1,2} = 0.1$, and $\omega = 0.025$. This same is approximately $15\xi_1 \times 15\xi_1$ or $200nm \times 200nm$.
- For example 2 $J_a = 7$, the superconductivity is improved, $|\psi_i|_{max} \leq \sqrt{4max\{\eta, \nu^2\eta\} + max\{\tau_1, \tau_2\}}$
- For example 3 $J_a = 2.0$ and $\eta = 0.2$, the superconductivity is not completely destroyed but it is severely diminished
- For example 4 $J_a = 2.0$ and $\eta = 0.2$ but $\mathbf{H}_e = 0$ and $\eta_1 = 0.2$. This shows a vortex anti vortex pair annihilating
- For example 5 we have $J_a = 2.0$ and $\eta = 0.2$ but $\mathbf{H}_e = 0$, and see as the previous figure predicts, the superconductivity is improved in a lower field.

The End